

Penalized Loss-Sensitive Generative Adversarial Network

Emma Ambrosini Department of Computer Science Simmons College emma.ambrosini@simmons.edu

Abstract

The Loss-Sensitive Generative Adversarial **Network Penalized with Gradient (LS-GAN-PG)** is an improvement of LS-GAN that exploits the norm of gradient of loss function with respect to its domain as a mechanism to reduce the complexity of generative models and to decrease the chance of being over-fitted to the few training examples. The LS-GAN proposes a novel paradigm for training the classical GAN model that utilizes a loss function to quantify the quality of generated samples with constraint that cost of real images must be smaller than the cost of generated samples at least by amount of an adaptable margin between fake and real samples so the model can focus on improving poor ones (those with a higher loss margin value) This is something the original GAN was not capable of doing – its learning was based on probability and a *discriminator* rather than a unique loss calculation.



Generative Adversarial Networks – method of training generative models that utilizes a *generator* and *discriminator* which train & work against each other in a "minimax two-player game" [1]



to regularize

Marzieh Edraki Department of Computer Science University of Central Florida M.Edraki@knights.ucf.edu





Epoch 1

LS-GAN LS-GAN-PG

Guo-Jun Qi Department of Computer Science University of Central Florida GuoJun.Qi@ucf.edu

- Cost model Architecture Sequence of five layers of convolution with stride of 2 followed by batch normalization and Rectified linear *function* as nonlinearity
- Training process
 - We used **celebA** dataset, a massive collection celebrity face photos.
 - Adam optimizer has been used to train the generator and cost model iteratively
 - Batch size of 64
 - Maximum number of training epochs is 24



Epoch 4





Convergence Point



Discussion

NSF

Both the Tensorflow LS-GAN and LS-GAN-PG were able to run, learn, produce decent quality samples

Faster convergence in model with gradient penalty applied than without Sample quality in the penalized LS-GAN evened out and began to slightly decrease at around the eleventh epoch

Could be due to the penalty, regularization working

Related Works

Generative Adversarial Network [1] – proposal of generative network method of training in which a discriminative model works against the generative model in training, discerning between 'real' and 'fake' samples. The generator attempts to fool the discriminator by improving sample quality.

DC-GAN [2] – Deep Convolutional GAN the that applies batch normalization in generator to alleviate the vanishing gradient problem on deep models. Has a focus on unsupervised learning and use D as a feature extractor.

References [1] I. Goodfellow, J. Pouget-Abadie, M. Mirza, B. Xu, D. Warde-Farley, S. Ozair, A. Courville, and Y. Bengio, "Generative adversarial nets," in Advances in Neural Information Processing Systems, 2014, pp. 2672-2680.

[2] A. Radford, L. Metz, and S. Chintala, "Unsupervised representation learning with deep convolutional generative adversarial networks," arXiv preprint arXiv:1511.06434, 2015.

Image: <u>https://github.com/carpedm20/DCGAN-</u> tensorflow

[3] Guo-Jun Qi, "Loss-Sensitive Generative" Adversarial Networks on Lipschitz Densities", arXiv preprint arXiv:1701.06264, 2017

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Epoch

Epoch

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